

RESILIENT ABSTRACTION-BASED CONTROLLER DESIGN

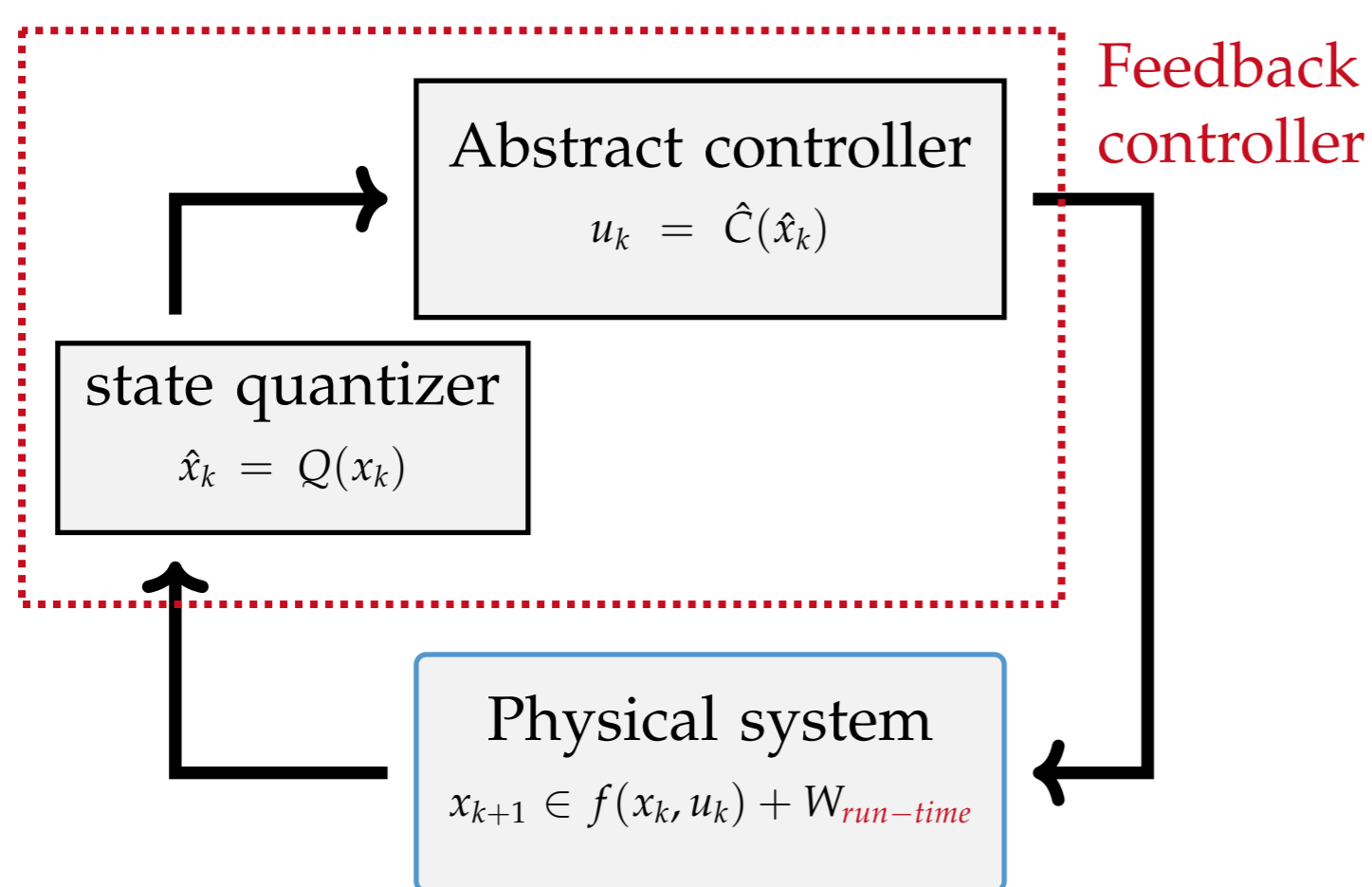
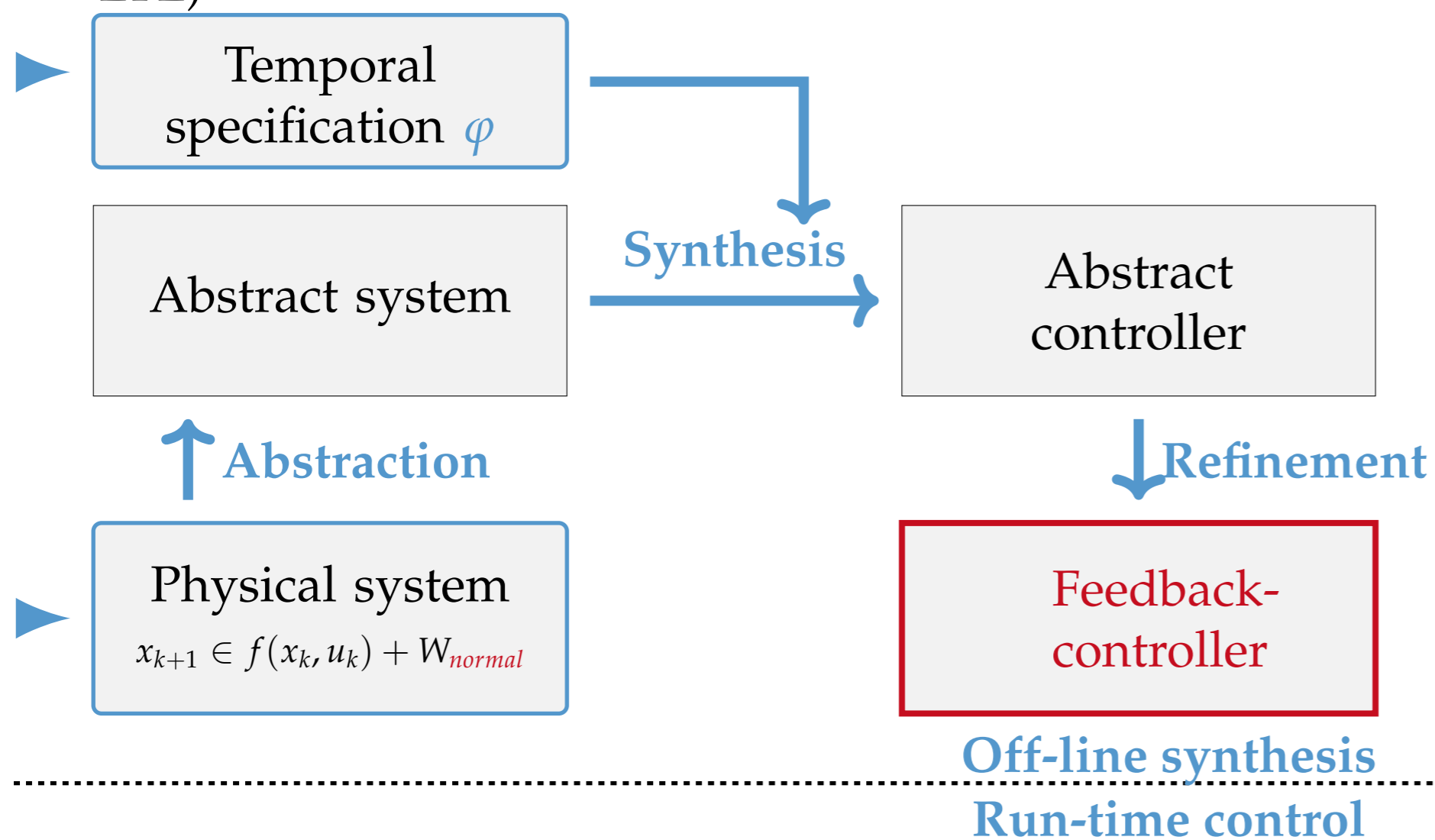
Stanly Samuel⁺, Kaushik Mallik^{*}, Anne-Kathrin Schmuck^{*}, and Daniel Neider^{*}

⁺Indian Institute of Science (IISc), India.

^{*}Max Planck Institute for Software Systems (MPI-SWS), Germany.

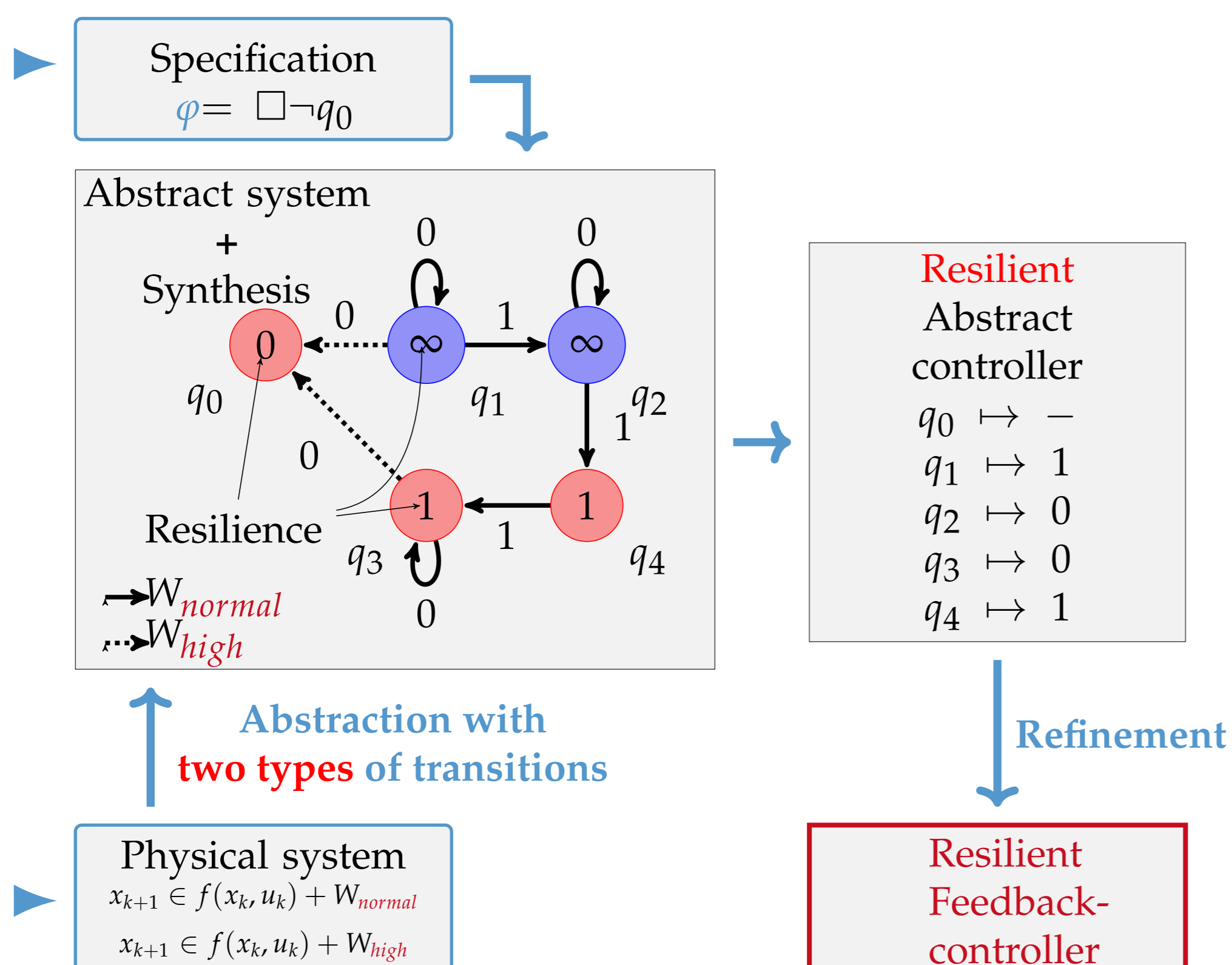
Abstraction-Based Controller Design (ABCD)

- **System:** Continuous non-linear dynamics
- **Specification:** Discrete, temporal properties (e.g. given in LTL)



Our contribution: Resilient ABCD

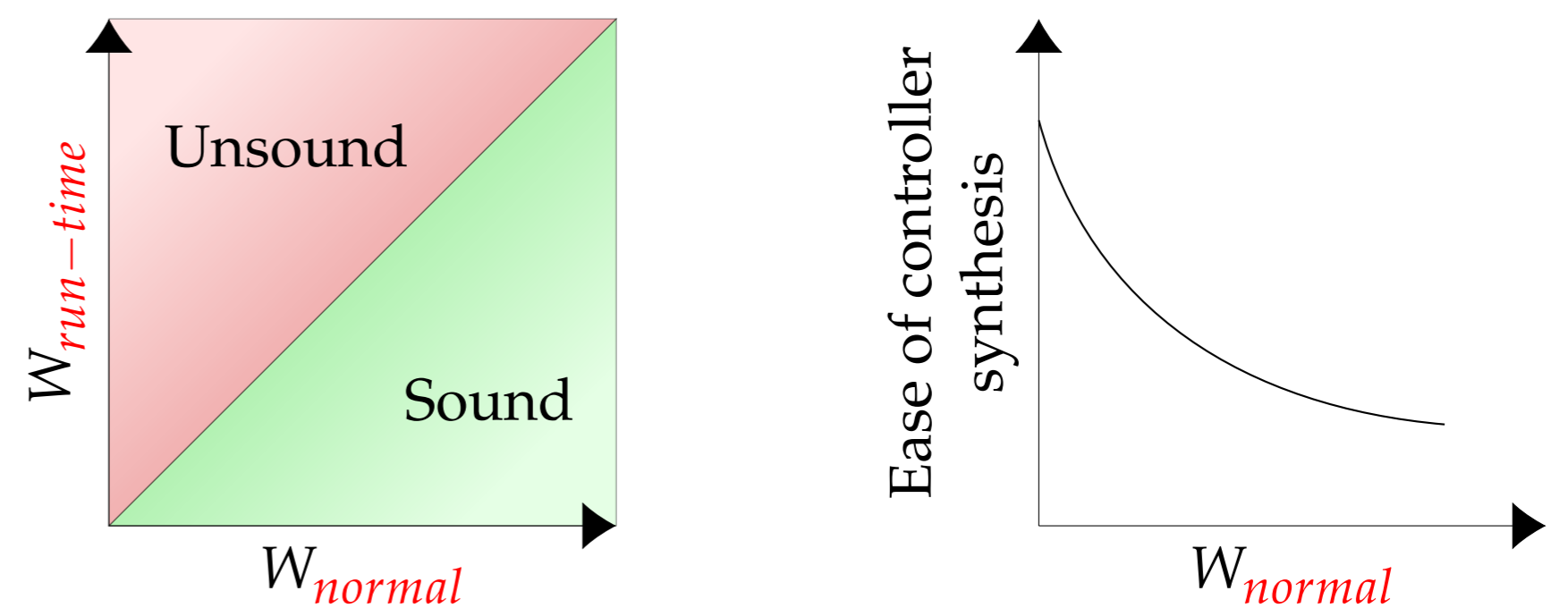
- A novel approach that guarantees soundness against normal operating disturbance range, and is **optimally resilient** against rarely occurring high-disturbance spikes.
- **Resilience** of a state is the max. number of high disturbances that the system can tolerate before violation of specification.
- We apply a game theoretic computation of resilience [1].



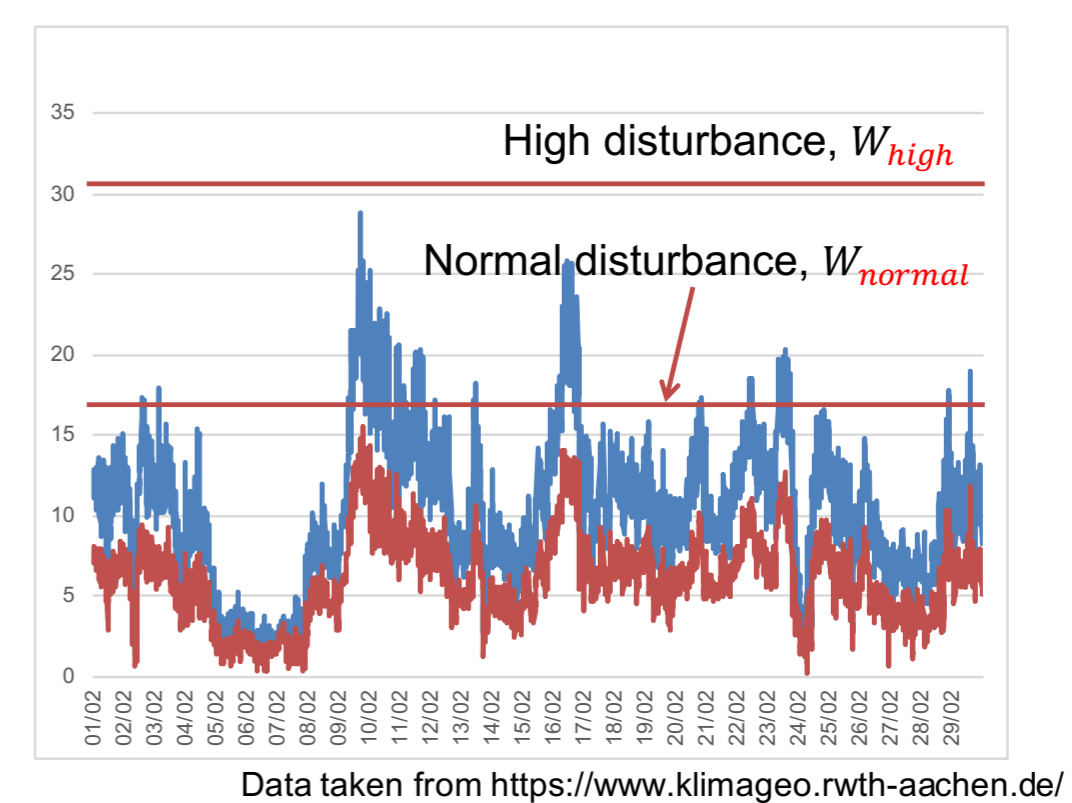
[1] Neider, D. et al., *Synthesizing optimally resilient controllers*, Acta Informatica, 2020.

Limitation of a uniform disturbance bound in ABCD

- A synthesized controller is sound if $W_{normal} \geq W_{run-time}$.
- For higher W_{normal} , finding a controller becomes difficult.



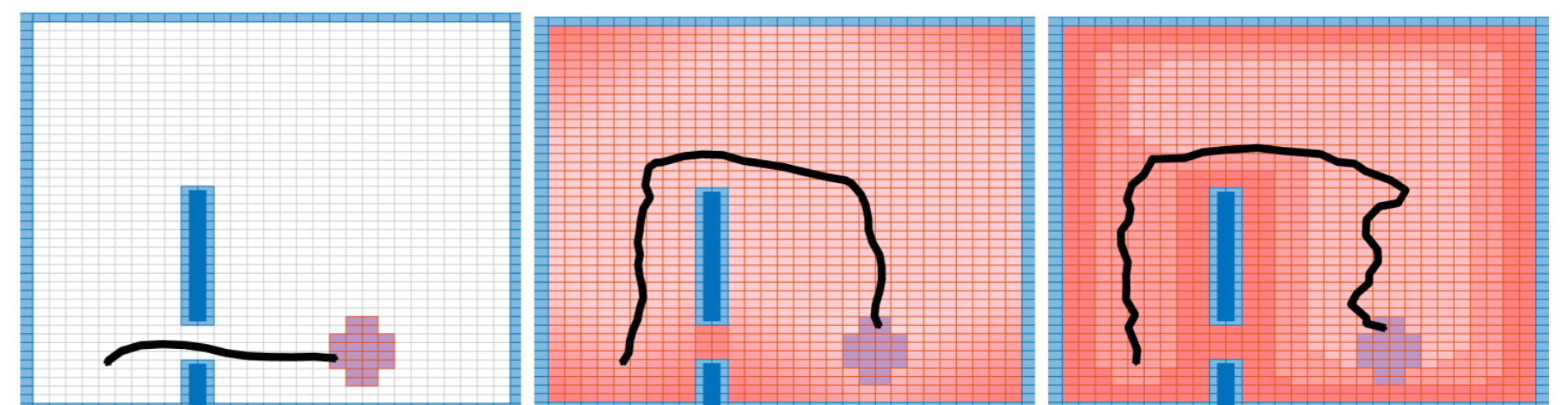
- In practice, we encounter milder disturbances most of the time, and more severe disturbances only occasionally. So it is impractical to assume the worst situation all the time.
- Recorded maximum (blue) and average (red) wind speed in m/s in Aachen-Hörn, Germany throughout February 2020:



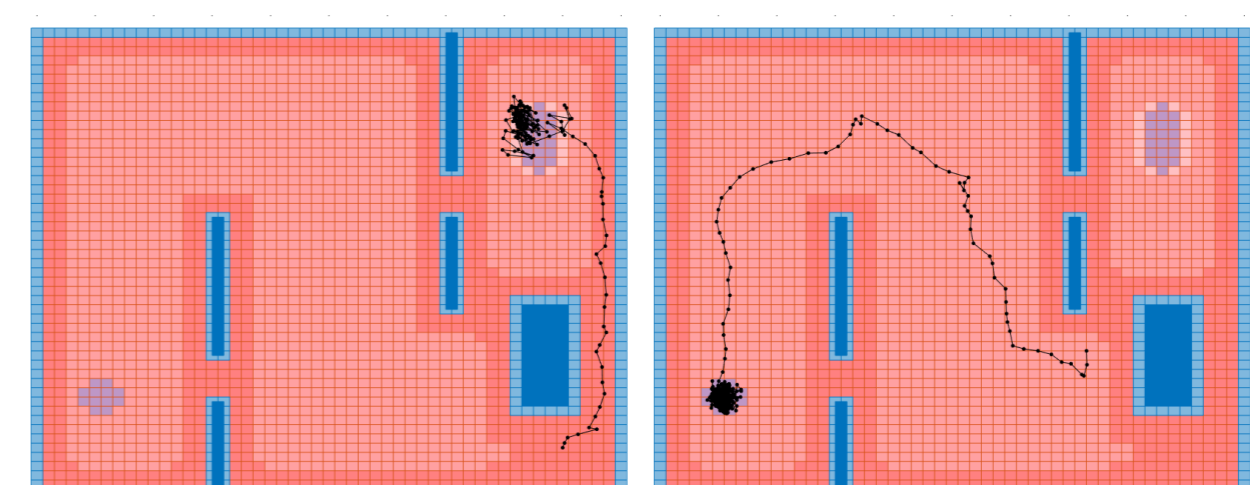
Data taken from <https://www.klimageo.rwth-aachen.de/>

Experimental evaluation

- Resilient ABCD is realized in our tool RESCOT which extends SCOTS with the notion of resilience as discussed.
- **Reach-while-avoid control:** Classical ABCD using SCOTS (left); Resilient ABCD using RESCOT with $(W_{normal}, W_{high}) = (0.05, 0.5)$ (middle) and $(W_{normal}, W_{high}) = (0.05, 2)$ (right). Lower resilient states are indicated in darker shade than higher resilient states. Strategies through the wide passage are more resilient.



- **Reach-while-avoid control with multiple targets:** Here targets are entirely chosen based on the reaching path resilience.



• Tool link: <https://bitbucket.org/stanlyjs/rescot/>

• Paper link: <https://people.mpi-sws.org/~kmallik/uploads/ResilientABCD2020.pdf>